Area of a Parallelogram

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April 20, 2021

Abstract

We show here how to relate the area of a parallelogram in the usual manner to how it can be represented in **geometric algebra**.

Our basic goal here is to represent the area of a parallelgram in geometric algebra, connecting it up with its standard presentation in geometry.

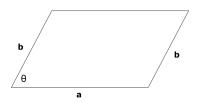


Figure 1. We have here a typical parallelogram.

In Fig. 1 we see a parallelogram whose area we know from high school math to be

Area Parallelogram =
$$ab\sin\theta$$
, (1)

where θ is the angle between sides **a** and **b**, and *a* and *b* are, respectively, the lengths of sides **a** and **b**.

Let's now place vectors on the sides of the parallelogram so that we can represent its area with a bivector (which better than a cross product).

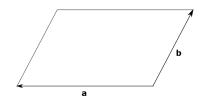


Figure 2. Written in bivector form, the area of the parallelogram can be expressed as $\mathbf{a} \wedge \mathbf{b}$.

Now, let **B** be any nonzero bivector represented as the wedge product of any two vectors (such as in Fig. 2). In geometric algebra, the *magnitude* of this bivector is defined by

$$\mathbf{B} \mid = [\langle \mathbf{B}^{\dagger} \mathbf{B} \rangle]^{1/2}, \qquad (2)$$

where $\langle \cdots \rangle = \langle \cdots \rangle_0$ means to take the scalar part of what's between the brackets. The symbol [†] is the *reverse* operator, which means to take the ordering of the vectors in reverse order. This operation distributes over addition. Scalars and vectors are invariant under the reverse operation. For clarification, with the a_i 's as vectors, we have the general relations:

$$(a_1 a_2 \cdots a_n)^{\dagger} = a_n \cdots a_2 a_1,$$

$$(a_1 \wedge a_2 \wedge \cdots \wedge a_n)^{\dagger} = a_n \wedge \cdots \wedge a_2 \wedge a_1$$

$$(a_1 \wedge a_2)^{\dagger} = -a_1 \wedge a_2.$$
(3)

Some additional background in geometric algebra may be of help. The *geometric product* of two vectors \mathbf{a} and \mathbf{b} is given as

$$\mathbf{a}\mathbf{b} = \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \wedge \mathbf{b} \,. \tag{4}$$

Solving for the bivector part, we have

$$\mathbf{a} \wedge \mathbf{b} = \mathbf{a}\mathbf{b} - \mathbf{a} \cdot \mathbf{b} \,. \tag{5}$$

We also need to know that

$$\mathbf{a} \cdot \mathbf{b} = \frac{1}{2} (\mathbf{a}\mathbf{b} + \mathbf{b}\mathbf{a}), \tag{6}$$

and, of course, the familiar relation from vector algebra,

$$\mathbf{a} \cdot \mathbf{b} = ab\cos\theta \,. \tag{7}$$

Now, for any two multivectors A and B

$$\langle AB \rangle^{\dagger} = \langle B^{\dagger}A^{\dagger} \rangle \,. \tag{8}$$

As a corollary, if A and B are both bivectors, then

$$\langle AB \rangle^{\dagger} = \langle (-B)(-A) \rangle = \langle BA \rangle.$$
⁽⁹⁾

My first task is to show that $|\mathbf{B}|$ is the area of the bivector parallelogram, and is given as $ab \sin \theta$. For convenience, I'll start with $|\mathbf{B}|^2$ where $\mathbf{B} = \mathbf{a} \wedge \mathbf{b}$.

$$\mathbf{B}|^{2} = \langle \mathbf{B}^{\dagger} \mathbf{B} \rangle$$

$$= \langle (\mathbf{a} \wedge \mathbf{b})^{\dagger} \mathbf{a} \wedge \mathbf{b} \rangle$$

$$= \langle (\mathbf{a} - \mathbf{a} \cdot \mathbf{b})^{\dagger} (\mathbf{a} \mathbf{b} - \mathbf{a} \cdot \mathbf{b}) \rangle$$

$$= \langle (\mathbf{b} \mathbf{a} - \mathbf{a} \cdot \mathbf{b}) (\mathbf{a} \mathbf{b} - \mathbf{a} \cdot \mathbf{b}) \rangle$$

$$= \langle \mathbf{b} \mathbf{a} \mathbf{a} \mathbf{b} - \mathbf{a} \cdot \mathbf{b} (\mathbf{b} \mathbf{a} + \mathbf{a} \mathbf{b}) + (\mathbf{a} \cdot \mathbf{b})^{2} \rangle$$

$$= \langle \mathbf{a}^{2} \mathbf{b}^{2} - 2(\mathbf{a} \cdot \mathbf{b})^{2} + (\mathbf{a} \cdot \mathbf{b})^{2} \rangle$$

$$= a^{2} b^{2} - a^{2} b^{2} \cos^{2} \theta$$

$$= a^{2} b^{2} \sin^{2} \theta. \qquad (10)$$

On taking square roots of both sides, this result agrees with what we knew from (1). Now, a useful corollary: if A is a scalar or a vector, then

$$A^{\dagger} = A \,. \tag{11}$$

My last task is to show that

$$|\mathbf{B}| = |\mathbf{B} \cdot \boldsymbol{\sigma}_1 \wedge \boldsymbol{\sigma}_2|, \qquad (12)$$

where σ_1 and σ_2 are unit vectors along the x- and y-axes, respectively.

Next follows some useful prerequisite results: Let A and B be any two multivectors. If **h** is any multivector such that $\mathbf{hh}^{\dagger} = 1$, then

$$AB = A(1)B = A\mathbf{h}\mathbf{h}^{\dagger}B = (A\mathbf{h})(\mathbf{h}^{\dagger}B), \qquad (13)$$

which comes from the fact that the geometric product is associative! (Yay!) In particular, let $\mathbf{h} = \boldsymbol{\sigma}_1 \boldsymbol{\sigma}_2$, then $\mathbf{h} \mathbf{h}^{\dagger} = 1$. (Prove it! Hint: First, $\boldsymbol{\sigma}_1^2 = \boldsymbol{\sigma}_2^2 = 1$, and, second, $\mathbf{h} \mathbf{h}^{\dagger} = \boldsymbol{\sigma}_1 \boldsymbol{\sigma}_2 \boldsymbol{\sigma}_2 \boldsymbol{\sigma}_1$, and then employ associativity carefully and remember that scalars commute with any multivector.) So,

$$AB = A(1)B = (A\boldsymbol{\sigma}_1\boldsymbol{\sigma}_2)(\boldsymbol{\sigma}_2\boldsymbol{\sigma}_1B).$$
(14)

Now,

$$\mathbf{B}|^{2} = \langle \mathbf{B}^{\dagger} \mathbf{B} \rangle
= \langle \mathbf{B}^{\dagger} \sigma_{1} \sigma_{2} \sigma_{2} \sigma_{1} \mathbf{B} \rangle
= \langle (\mathbf{B}^{\dagger} \sigma_{1} \sigma_{2}) (\sigma_{2} \sigma_{1} \mathbf{B}) \rangle
= \langle (\mathbf{B}^{\dagger} \cdot \sigma_{1} \wedge \sigma_{2}) (\sigma_{2} \wedge \sigma_{1} \cdot \mathbf{B}) \rangle
= (\mathbf{B}^{\dagger} \cdot \sigma_{1} \wedge \sigma_{2}) \langle (\sigma_{2} \wedge \sigma_{1} \cdot \mathbf{B}) \rangle
= (\mathbf{B}^{\dagger} \cdot \sigma_{1} \wedge \sigma_{2}) \langle (\sigma_{2} \wedge \sigma_{1} \cdot \mathbf{B}) \rangle^{\dagger} \text{ from (11)}
= (\mathbf{B}^{\dagger} \cdot \sigma_{1} \wedge \sigma_{2})^{2} \text{ from (8)}
= |\mathbf{B}^{\dagger} \cdot \sigma_{1} \wedge \sigma_{2}|^{2}
= |\mathbf{B} \cdot \sigma_{1} \wedge \sigma_{2}|^{2}.$$
(15)

We get (12) by taking square roots of both sides. QED

Additional note. The reader who is not familiar with geometric algebra and wedge products, can reference on-line sources through the search string 'wedge product'. The main reference book is New Foundations for Classical Mechanics by David Hestenes (Kluwer Academic Publishers). An online reference is

http://geocalc.clas.asu.edu/pdf-preAdobe8/PrimerGeometricAlgebra.pdf